

ABSTRACT OF THE DISCLOSURE

A surgical instrument has a tool located at the distal instrument end, a stationary first grip part at the proximal instrument end, a second grip part adjustable in an axially guided manner in the form of a reel, and an actuation element for the tool. The actuation element in connection with the second grip part is axially adjustable on adjustment of the second grip part. For improving the handling of the instrument, it is envisaged that, by way of a lever system linked onto the second grip part and a stationary part of the instrument, the adjustment path of the second grip part is geared down and the force exerted onto the second grip part is transmittable, geared up, to the actuation element.

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